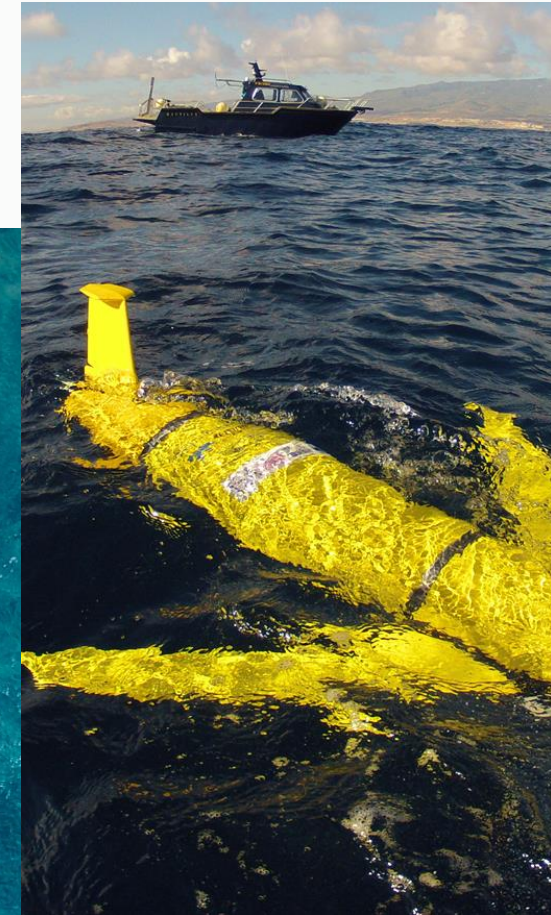


National  
Oceanography  
Centre

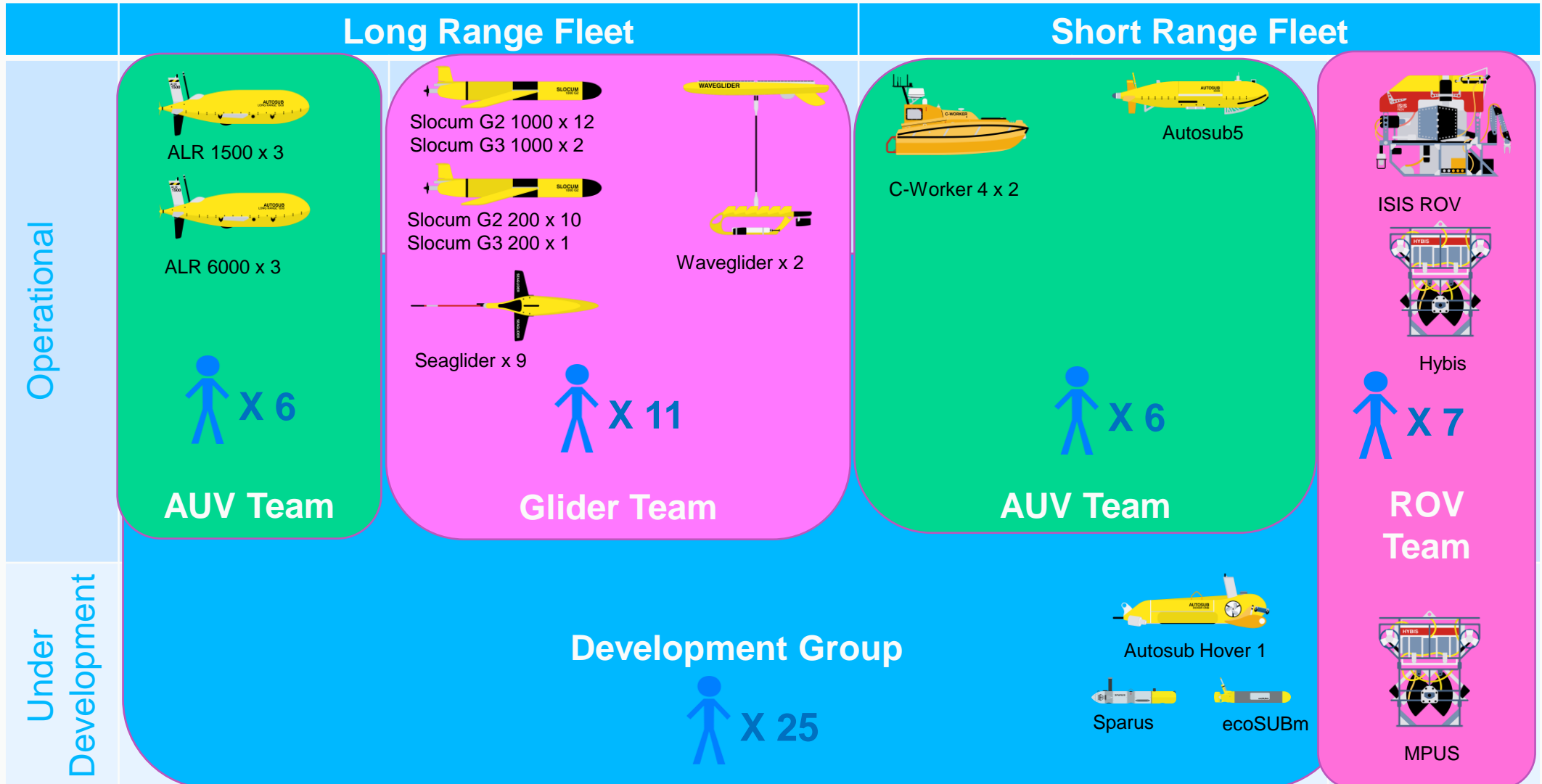


**OVER THE HORIZON AND  
UNDER ICE ADVANCES IN  
MARINE ROBOTICS FROM  
NOC**

**26-SEP-2024**

**MATT TIAHLO**

# NMF MARINE ROBOTICS AND AUTONOMOUS SYSTEMS (MARS) TEAMS



## 3 x Autosub Long Range 6000 (ALR6000)

- 2 x Pressure Vessel
- 38kWhrs Primary LTC Batteries
- 6000m depth rating
- Mass  $\approx$  800 kg
- Length  $\approx$  3.5m
- Top Speed  $\approx$  1m/s
- Max Range  $\approx$  **2000km**

- 1 x Pressure vessel
- 95kWhrs Primary LTC batteries
- 1500m depth rated
- Mass  $\approx$  800 kg
- Length  $\approx$  3.5m
- Top Speed  $\approx$  1m/s
- Max Range  $\approx$  **6000km**

## 3 x Autosub Long Range1500 (ALR1500)

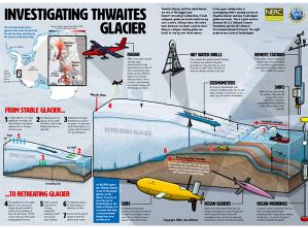
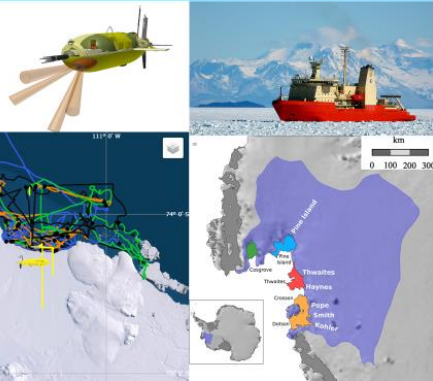


# RECENT ALR MISSIONS

## TARSAN – Q1 '22



Multi-day deployment of ALR1 from the Nathaniel B Palmer under Dotson Glacier as part of TARSAN International Thwaites Glacier Collaboration  
 Longest track was 40km in under the ice flying at circa 100m altitude

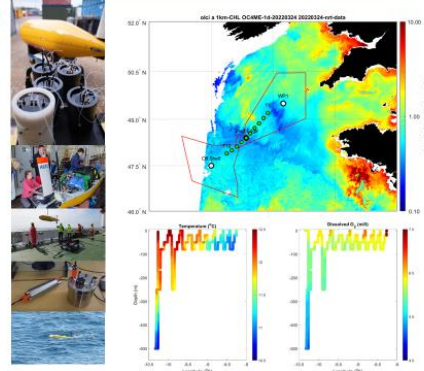


<https://thwaitesglacier.org/projects/tarsan>

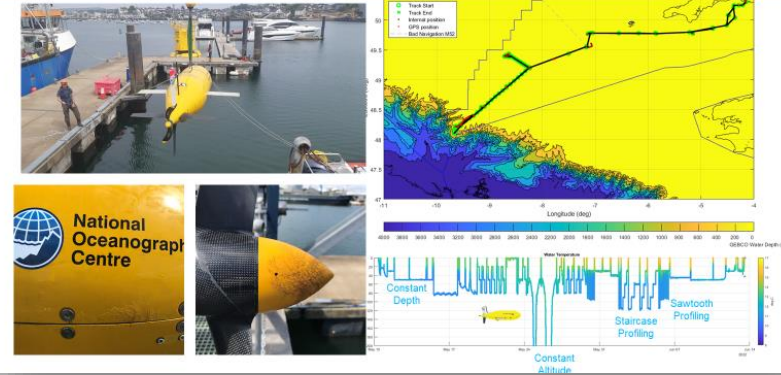
## BIOGEOCHEMISTRY (DY149) – Q1 '22



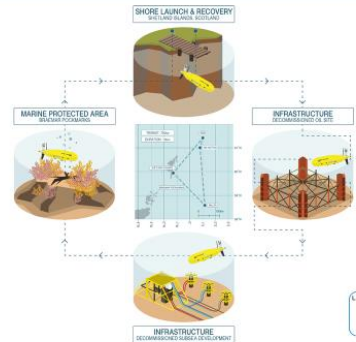
<b>AUV</b>	ALR2
<b>Depth Rating</b>	8000 m (Nominal) Currently de-rated to 600 m for sensor payload
<b>Energy</b>	Lithium Thiocyl Chloride (~10 Days)
<b>System sensors</b>	<ul style="list-style-type: none"> <li>300 kHz RDI ADCP</li> <li>PNI Magnetic Heading Sensor</li> <li>CTD SBE 52</li> <li>ADCP's as per system ADCP's</li> <li>DO SBE 43F</li> </ul>
<b>Science sensors</b>	<ul style="list-style-type: none"> <li>AutoNuts – Nutrients                             <ul style="list-style-type: none"> <li>LOC Nitrate</li> <li>LOC Silicate</li> <li>LOC Iron (Chemiluminescent)</li> <li>LOC Iron</li> <li>LOC Nitrite</li> <li>LOC Phosphate</li> </ul> </li> <li>Carcass – Carbonate                             <ul style="list-style-type: none"> <li>LOC pH</li> <li>LOC TA</li> <li>LOC DIC</li> <li>ANB pH</li> </ul> </li> <li>Stafes-App – Primary Productivity</li> </ul>



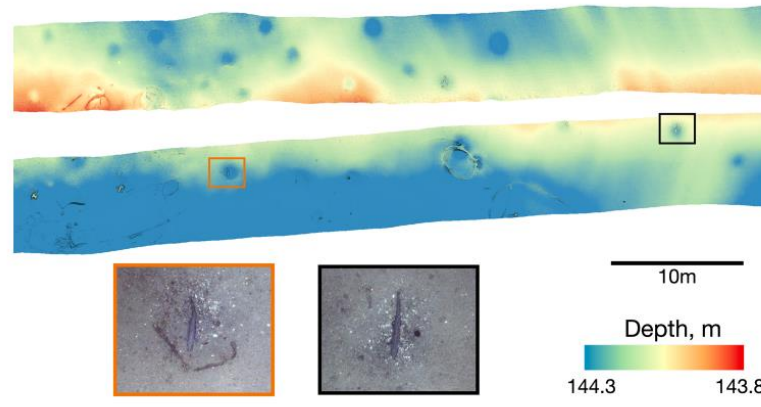
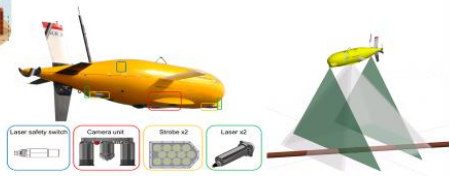
## LONG DISTANCE PROVING TRIAL (LDPT) APRIL 22



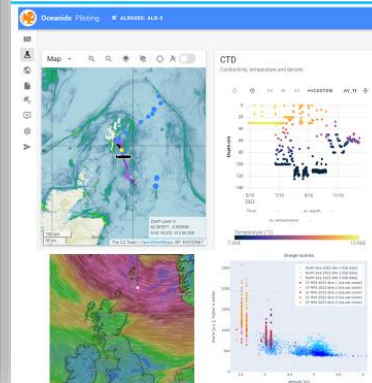
## INSITE ATSEA (SEPT/OCT 2022)



- INSITE is an independent science programme examining the effects of man-made structures in the North Sea
- The Autonomous Techniques for anthropogenic Structure Ecological Assessment ATSEA project is aiming to assess the feasibility and efficacy of fully autonomous monitoring of multiple decommissioning-related sites without the aid of a support vessel by demonstrating the use of an existing shore-launched, long-range, fully autonomous underwater vehicle for marine environmental survey.



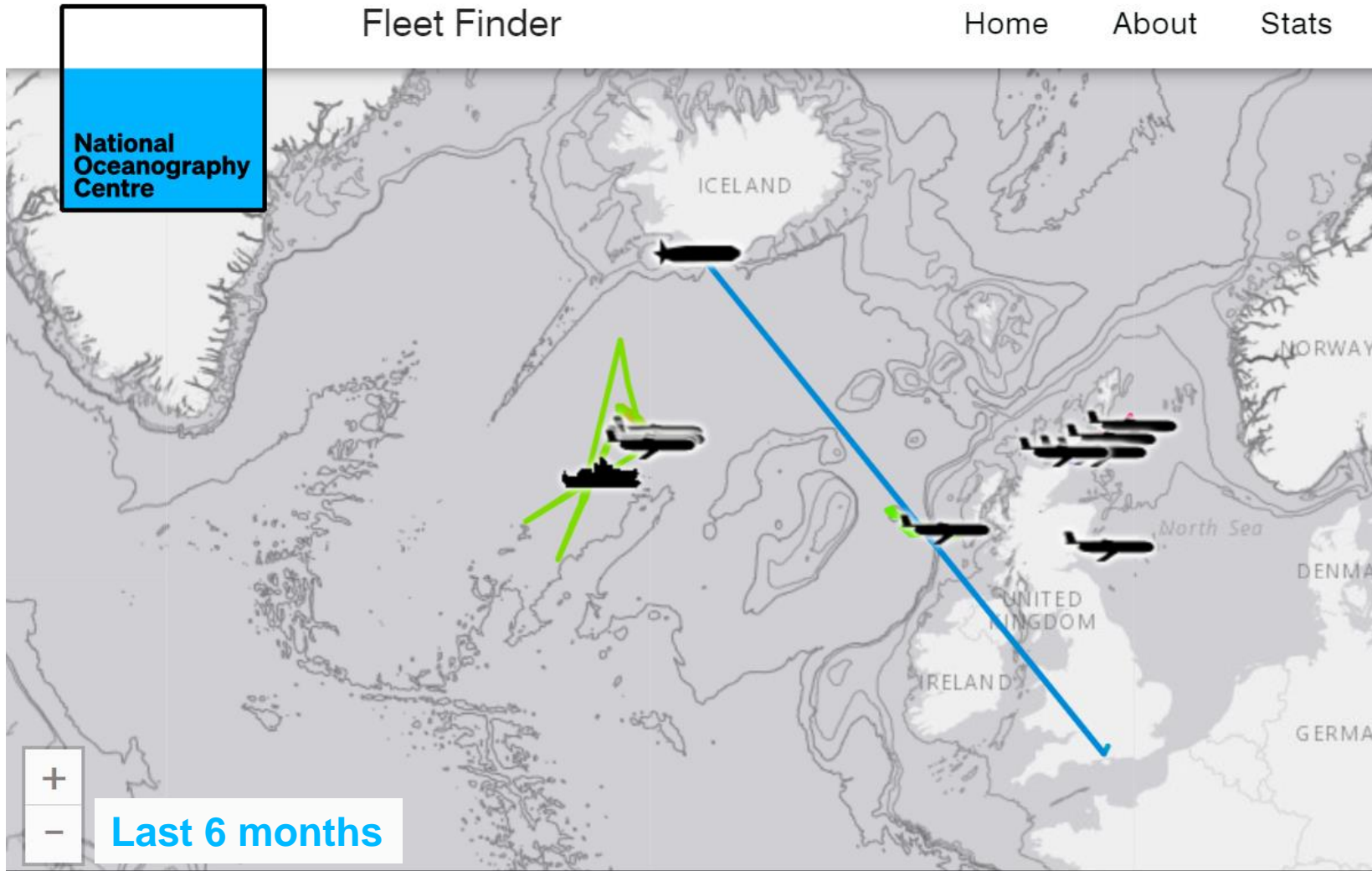
## OCTOBER 2023 CENTRAL FLADDON MPA SURVEY



- ALR4 was deployed from Lerwick on the 4<sup>th</sup> October, following a short tow the AUV traversed 110 km to the Central Fladdon MPA.
- Within the MPA the system took ~1M images with the BioCAM imaging system flying between 3.5m and 4.5m altitude from the seabed.
- Having completed the survey the AUV transited back to Lerwick. Recovery was delayed by strong Autumn gales which the AUV waited out loitering subsea.



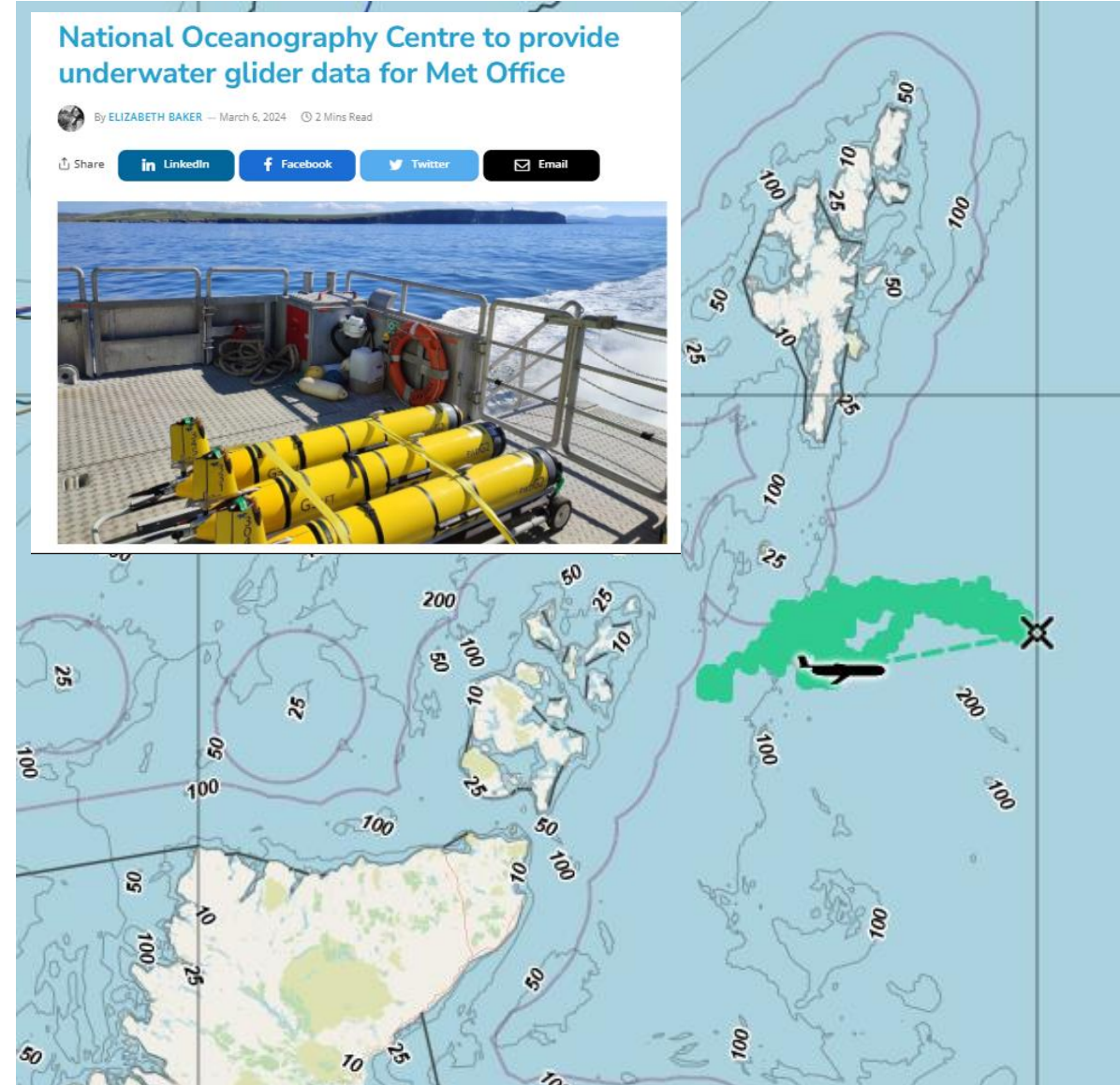
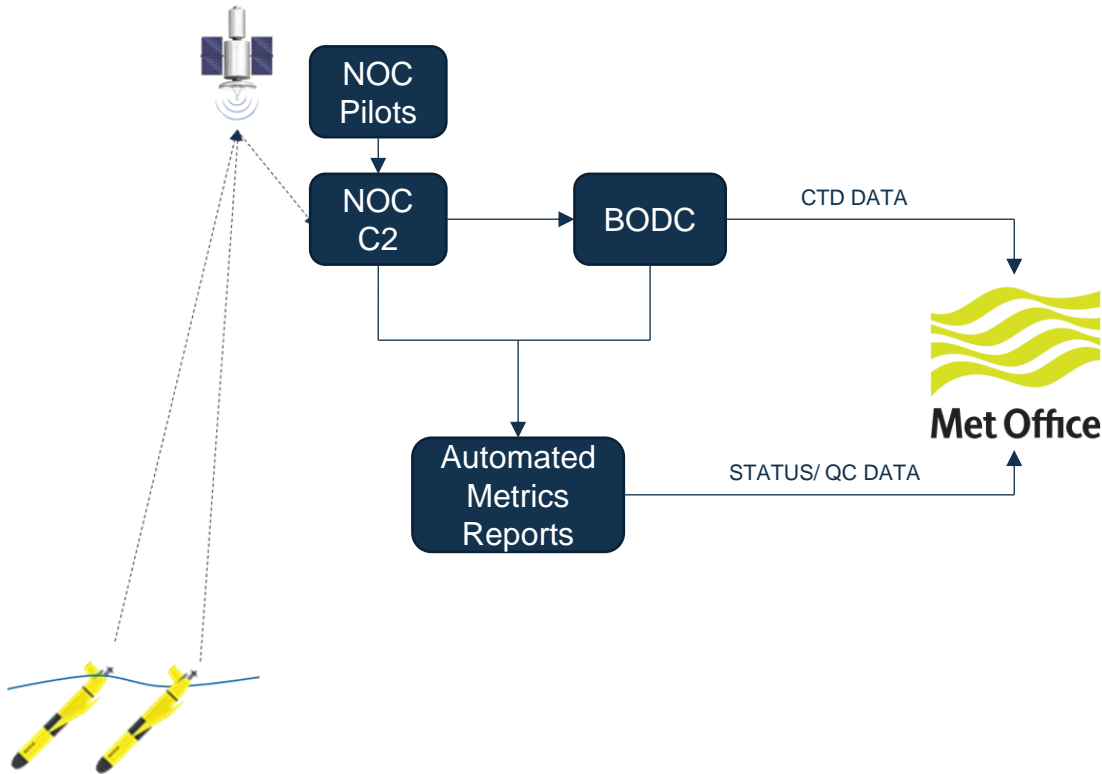
# WHAT IS HAPPENING NOW (ISH)



# MOGLI - UK MET OFFICE GLIDER PROJECT CONTINUOUS PRESENCE ON THE JONSIS LINE

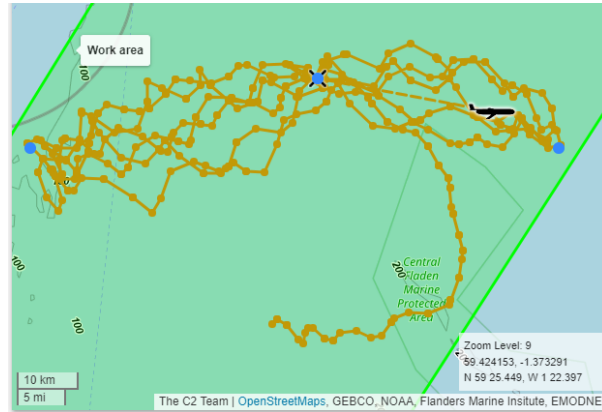
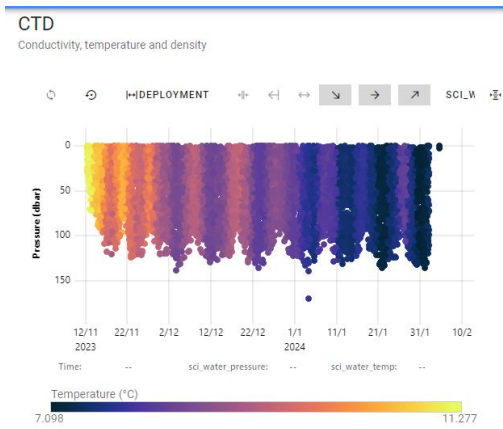


- Patrolling Western end of the JONSIS Line for last 21 months
- Providing Near Real Time Conductivity, Temperature, & Depth (CTD) Data that is fed into the AMM 15 ocean model.



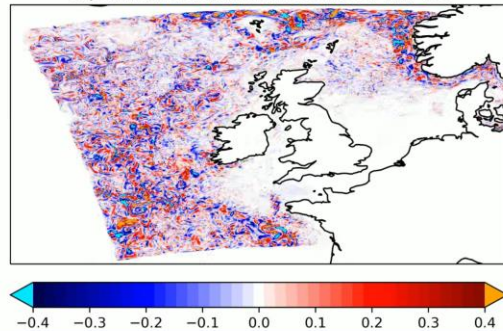
# MOGLI – THE GOOD AND THE BAD

## The Good – positive impact on model performance



## AMM15 Results – surface temperature field difference over time

experiment-control 20221028 model run: -36



## The Bad – We lost a glider



We had factored a loss into the project

# BIPOLE (DEC 23-FEB 24)

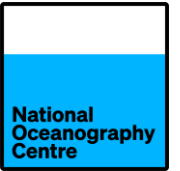


Natural Environment Research Council

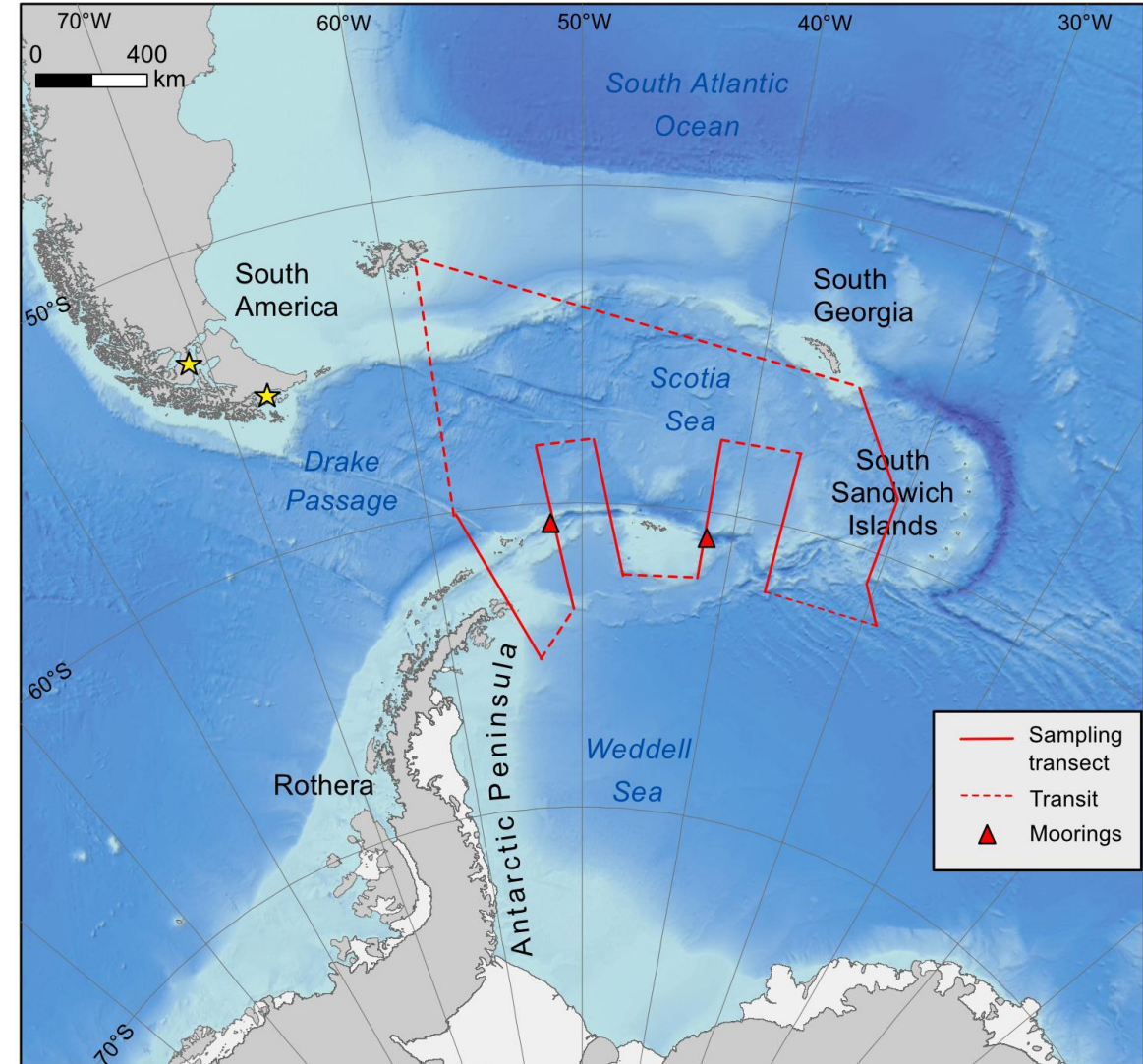


British Antarctic Survey

NATURAL ENVIRONMENT RESEARCH COUNCIL



- BIPOLE is an interdisciplinary NERC programme examining biogeochemical processes and ecosystem function in polar ecosystems.
- An Observational campaign in the Weddell sea using of ships, moorings and gliders
- Gliders made short duration missions under retreating sea ice using a Backseat Driver and upwards altimeter to enable this capability.

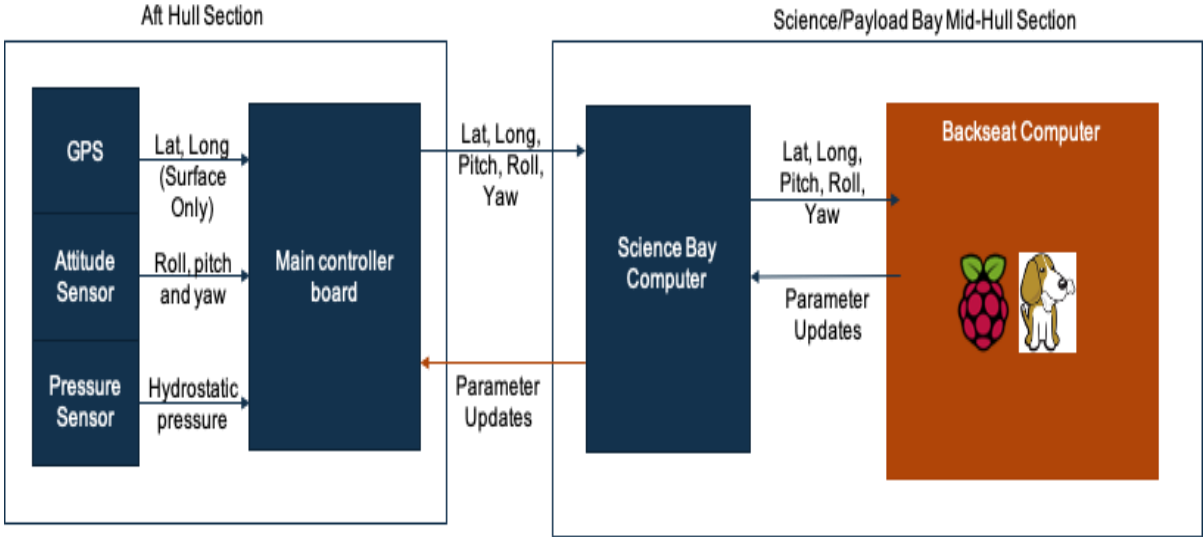




# BIPOLE – GLIDER BACK SEAT DRIVER

## Goal

Develop ice coping strategies and add to a “backseat driver” to control the gliders under ice

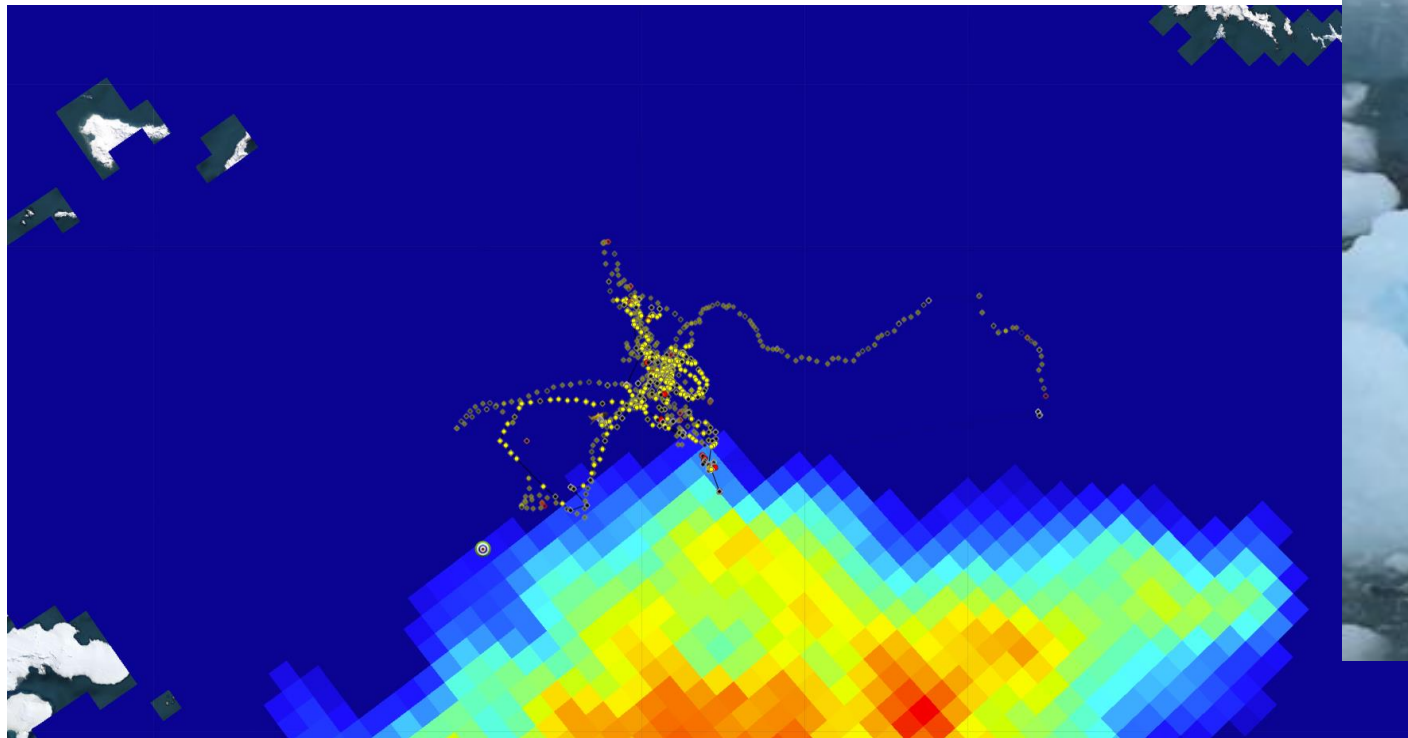


### Ice sensing strategies

• Median temperature	• Ice draft	• Ice edge
<p> <math display="block">\begin{cases} \text{Ice: } \text{Median temp} &lt; \text{Thresh temp} \\ \text{No ice: } \text{Median temp} &gt; \text{Thresh temp} \end{cases}</math> </p>	<p>                     The ice draft <math>D_i</math> is  <math display="block">D_i = D_p - D_a \cdot \cos(\theta) \in \begin{cases} (-\infty, b), \text{ uncertainty} \\ (b, +\infty), \text{ ice area} \end{cases}</math> <math>D_p</math>: CTD depth  <math>D_a</math>: Upward-looking altitude  <math>\theta</math>: Angle of the upward-looking altimeter  <math>b</math>: The minimum detectable ice draft                 </p>	<p>                     Boundary points location  <math>d = f(\text{mission time, ice edge})</math> </p>
<p>Figure 5. Measuring the median temperature of mixed layer.</p>	<p>Figure 6. Ice draft which is the difference between CTD depth and upward-looking altitude.</p>	<p>Figure 7. Ice edge for defining the boundary points between ice area and open water area.</p>

# GLIDER OPERATIONS – IT WAS VERY DIFFICULT

Piloting using satellite data to get into and out  
of the marginal ice zone



Gliders just before being “munched” by the ice




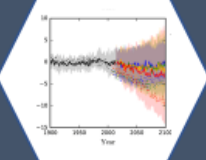
Lots of lessons to learn about the  
environment and best approach to it

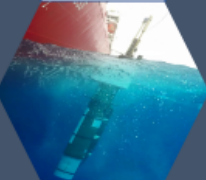
# THE BIOCARBON PROGRAMME

## The major science questions



 How does marine life affect the ability of seawater to absorb carbon dioxide, and how will this change?

 How will the rate at which marine life consumes carbon dioxide change?

 How long can marine life store carbon in the ocean and how will climate change affect this?

## BIO-Carbon programme



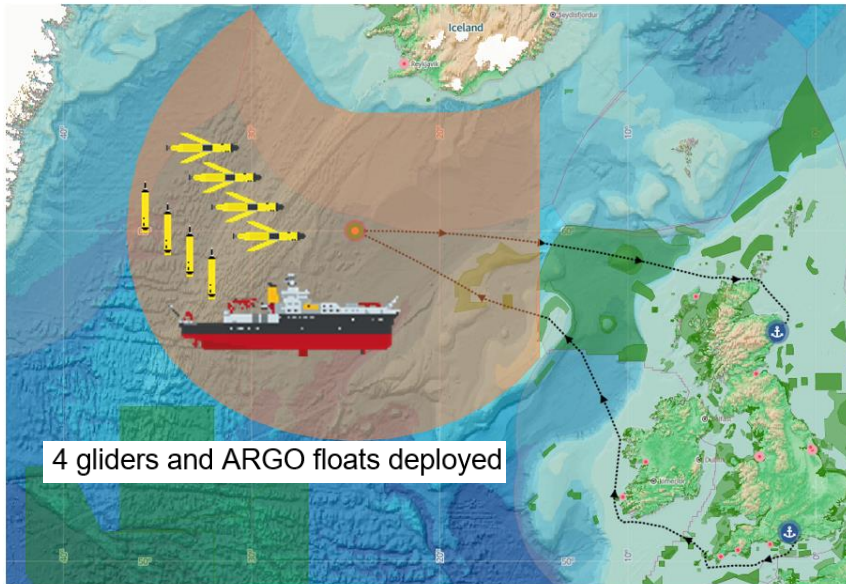
- Focussed on understanding role of marine life in ocean carbon storage and how this will alter under climate change
- Baseline information necessary for many mCDR discussions
- Strategic Programme, £10.3M, spanning ~6 years, started 2022
- Nine projects already funded, including a gap analysis (BRICS)
- Three fieldwork projects - 6 months of activity just begun
- Final stage will be aimed at modelling and synthesis

# THE BIOCARBON PROGRAMME

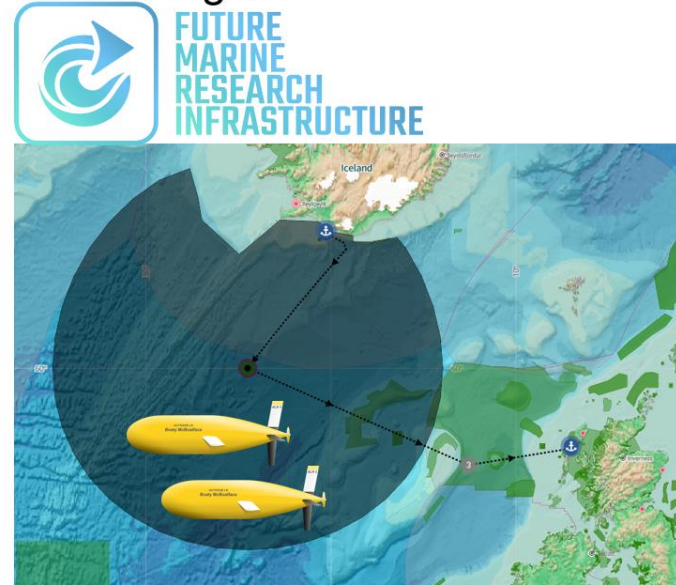


## Fieldwork

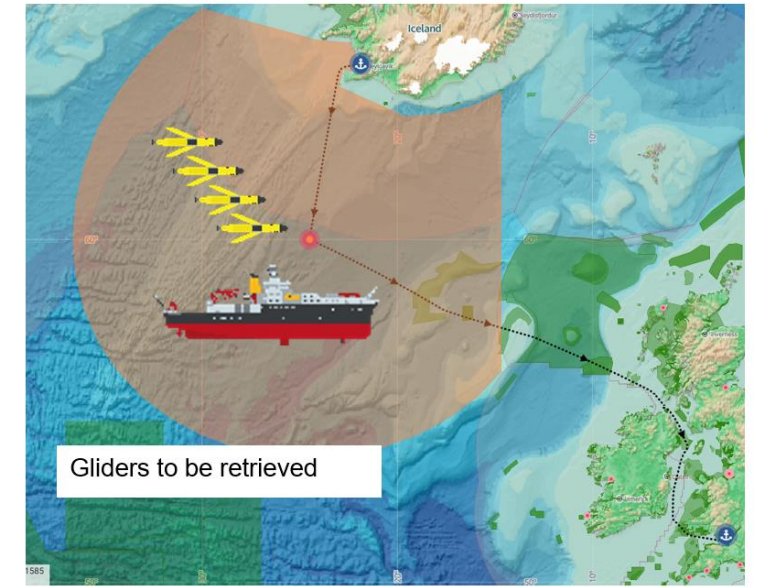
Spring cruise – DY180  
21 May – 27 June



BIO-Carbon-FMRI ALR mission  
June - August



Autumn cruise – JC269  
6 September – 13 October



# BIOCARBON ALR4



Natural Environment Research Council



FUTURE MARINE RESEARCH INFRASTRUCTURE



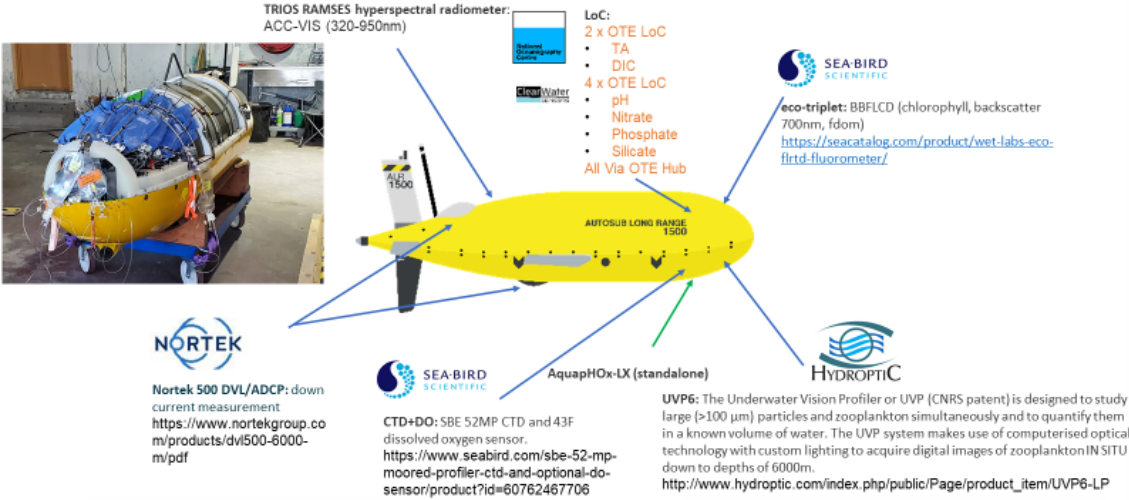
MiXed Layer ALR (ALR4)



Natural Environment Research Council



FUTURE MARINE RESEARCH INFRASTRUCTURE



## BIOCARBON ALR-4 OVERVIEW



Shore Launched  
 09.06.2024  
 Vestmannaeyjar,  
 Heimaey, Iceland

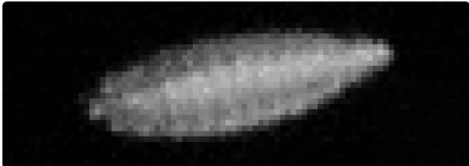
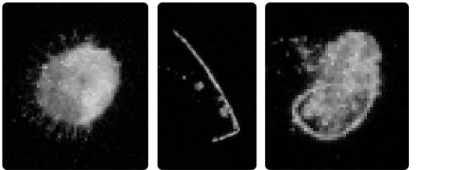
### First Trans-Basin Autosub Deployment

- >56 days on Mission 64% increase on previously demonstrated Endurance  
 >25 days energy remaining
- >2500km / 1350 Nautical Miles Travelled - 25% increase on previous best
- >250 Dives
- 59 Over-the-Horizon Missions Commanded and Controlled via Satellite



Shore Recovered  
 05.08.2024  
 Leverburgh, Harris,  
 United Kingdom

**Payload:**  
 CTD, Conductivity\*, Temperature\* and Pressure\*, + Dissolved Oxygen\*  
 6x in-situ Miniaturised Chemical Analysers; DIC\*, TA\*, pH\*, SiO<sub>4</sub>\*, PO<sub>4</sub>\*, & NO<sub>3</sub>\*  
 Laser Zooplankton Imaging system UVP6  
 Hyperspectral Radiometer  
 Up & Down ADCP, Acoustic Doppler Current Profilers  
 \*Near Real Time data telemetered via satellite.



### Down into the ocean's 'twilight zone' with Boaty McBoatface



Boaty McBoatface spent 55 days at sea before coming ashore in Scotland



# BIOCARBON ALR 6



Natural Environment Research Council



FUTURE MARINE RESEARCH INFRASTRUCTURE



## Profiling ALR (ALR6)



Natural Environment Research Council



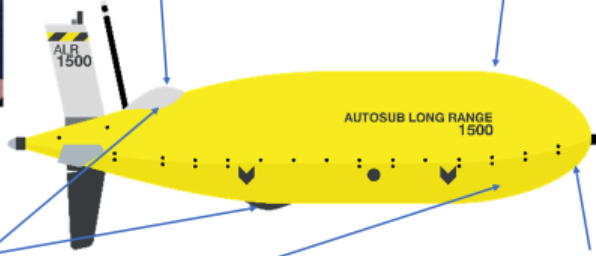
TRIOS RAMSES hyperspectral radiometer: ACC-VIS (320-950nm)



eco-triplet: BB2FL (with chlorophyll, backscatter 532nm and 70nm)  
<https://seacatalog.com/product/wet-labs-eco-flrtd-fluorometer/>



MicroRider: Turbulence Probe.  
<https://rocklandscientific.com/products/modular-systems/microrider/>



UVP6: The Underwater Vision Profiler or UVP (CNRS patent) is designed to study large (>100 μm) particles and zooplankton simultaneously and to quantify them in a known volume of water. The UVP system makes use of computerised optical technology with custom lighting to acquire digital images of zooplankton IN SITU down to depths of 6000m.  
[http://www.hydroptic.com/index.php/public/Page/product\\_item/UVP6-LP](http://www.hydroptic.com/index.php/public/Page/product_item/UVP6-LP)

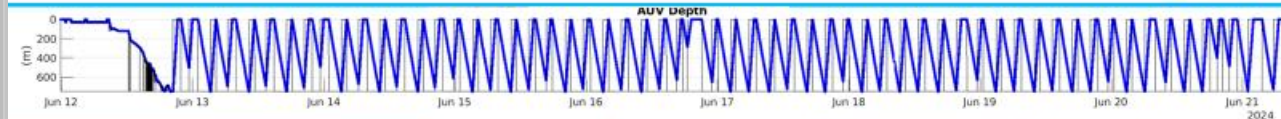


Nortek 500 DVL/ADCP: down current measurement  
<https://www.nortekgroup.com/products/dvl500-6000-m/pdf>



CTD+DO: SBE 52MP CTD and 43F dissolved oxygen sensor.  
<https://www.seabird.com/sbe-52-mp-moored-profiler-ctd-and-optional-ds-sensor/product?id=60762467706>

## BIOCARBON ALR-6 OVERVIEW



Shore Launched  
 11.06.2024  
 Vestmannaeyjar,  
 Heimaey, Iceland



56 profiles to 500/750m  
 > 430 km  
 20 Missions



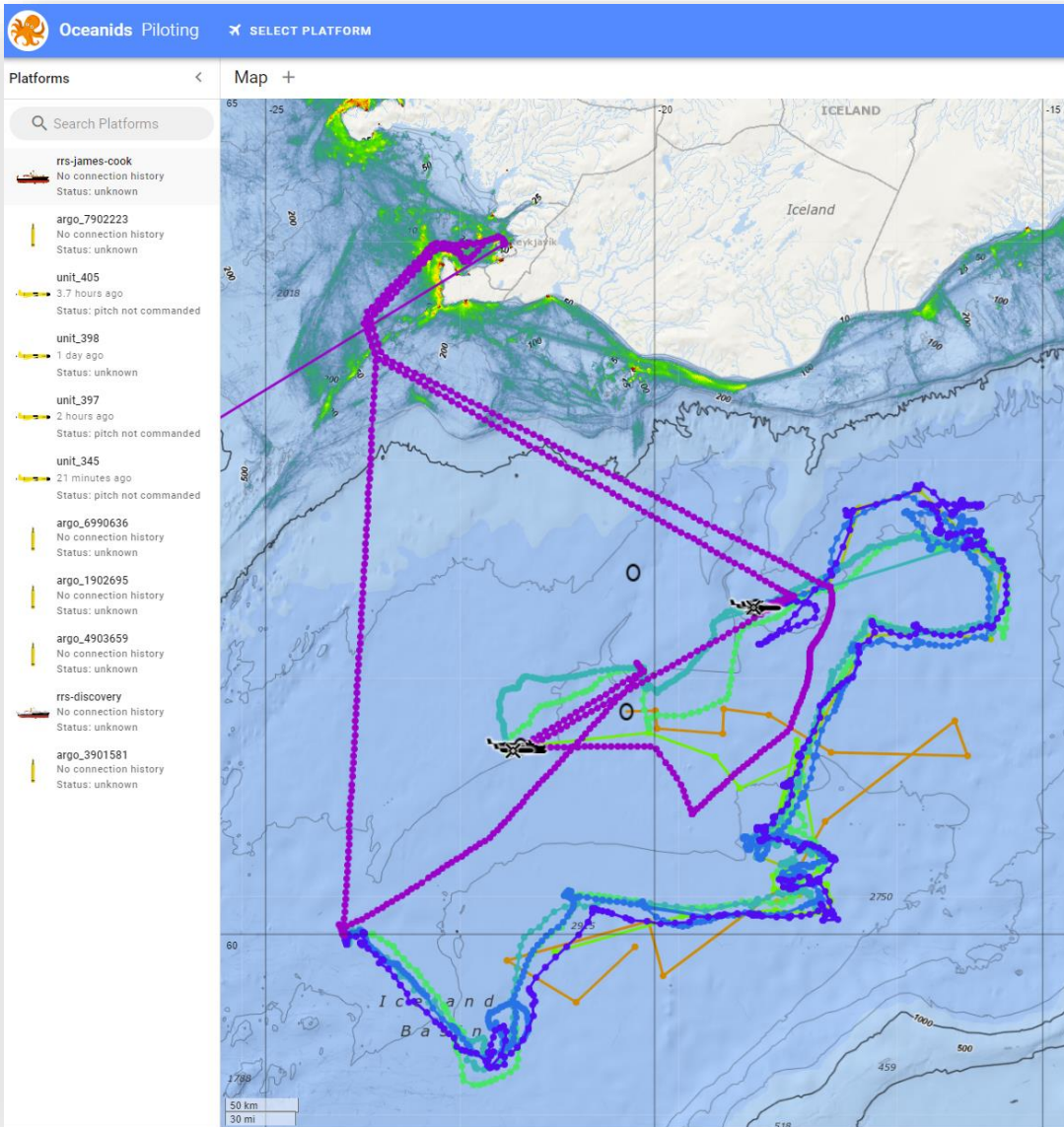
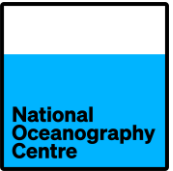
# WHAT'S HAPPENING NOW?



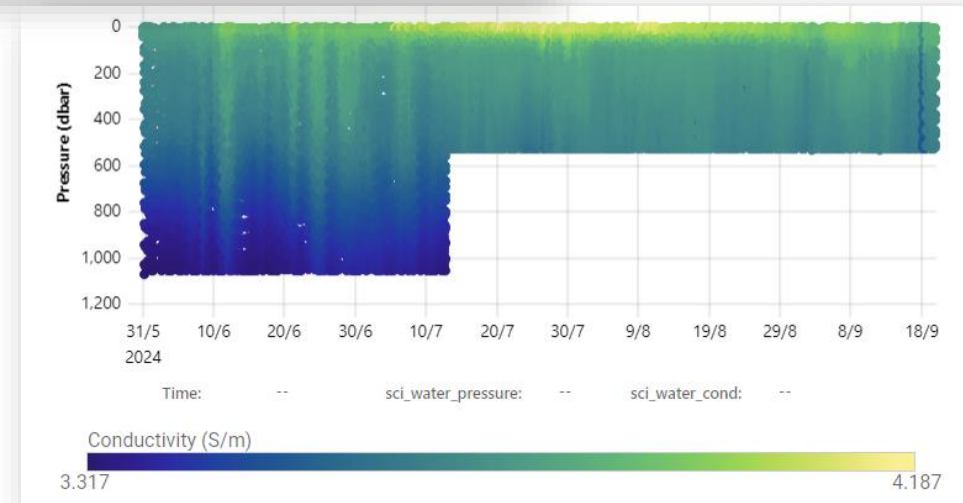
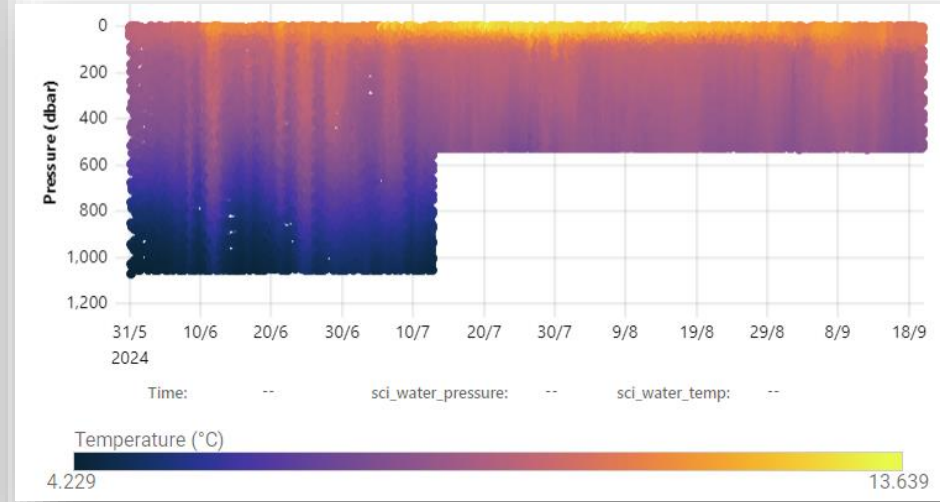
Natural Environment Research Council



FUTURE MARINE RESEARCH INFRASTRUCTURE



## Slocum Unit 397 (Nelson) Temperature and Conductivity



Follow progress on:  
<https://bio-carbon.ac.uk>  
<https://mars.noc.ac.uk/>

# FINAL THOUGHTS – AND LESSONS LEARNED

- Marine Robotics are just other tools in the toolbox they don't replace ships but augment them
- You will lose them at some points
- To get the best out of marine robotics you need to have:
  - Staff with a deep understanding of the tech
  - Detailed knowledge of the environment you are operating in
  - Good processes and tools to support the staff
  - Luck is also always useful
- Combined ship operations and autonomy provide interesting opportunities





