

Degree: 0.25° x 0.5° Depth Range: < 1m - 635m Operating Frequency: 200 - 700 kHz Swath Width: Up to 170° Receiver Beams: 1024 beams

Kongsberg EM712

Sonar: Multibeam Degree: 0.25° x 0.5°, full performance Depth Range: 3m - 3,600m Operating Frequency: 40 - 100 kHz Swath Width: up to 5.5 times the depth Receiver Beams: 1600 beams

Kongsberg EM124

Sonar: Multibeam Degree: 0.50 x 10 Depth Range: 20m - 11,000m Nominal Frequency: 12 kHz Operating Frequency: 10.5 - 13.5 kHz Swath Width: up to 6 times the depth Receiver Beams: 1600 beams

Sonar: ADCP Frequency: 300 kHz Profiling Range: 154m Max Bottom Tracking: 253m Velocity Range: ± 5 m/s Velocity Accuracy: + 0.5 cm/s

Teledyne RDI OS38

Sonar: ADCP Frequency: 38 kHz Max Profiling Range: >1,000m Max Bottom Tracking: 1,700m Velocity Range: ±7 m/s Velocity Accuracy: + 0.5 cm/s

Kongsberg SBP 29

Sonar: Sub Bottom Profiler Degree: 30 x 30 Depth Range: 1m - 11,000m Max Penetration: >200m Operating Frequency: 2 - 9 kHz Pulse Length: 2 to 100ms

Kongsberg EA640

Sonar: Singlebeam Echosounder Frequency: 12 kHz Depth Range: 1m - 11,000m

Kongsberg EA440

Sonar: Hydrophone Frequency: 10 - 90 kHz

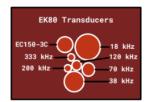
Simrad EK80

W/ EC150-3C ADCP

Sonar: Mid-water echosounder Frequency Range: 18 - 333 kHz

Valeport Mini SVS

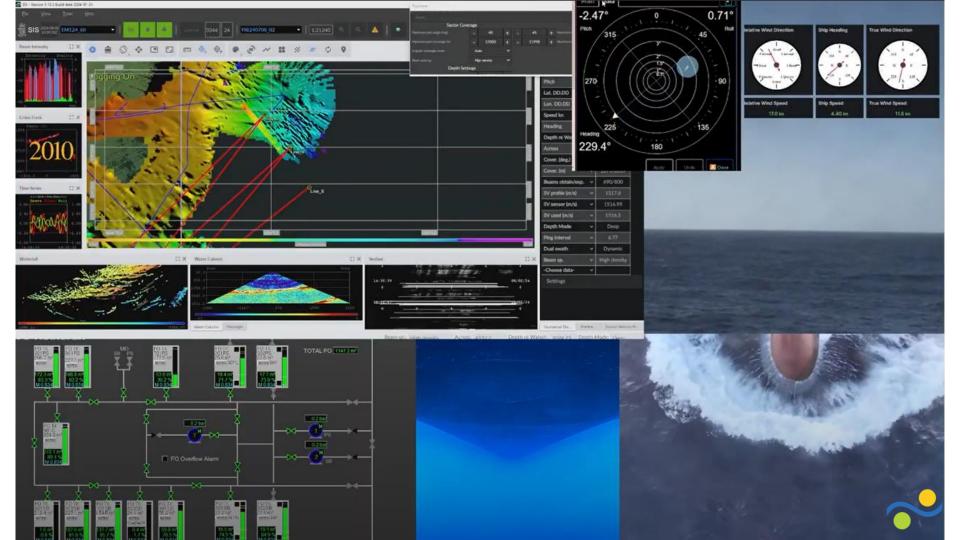
Sonar: Sound Velocity Frequency: 2.5 MHz Range: 1375 - 1900 m/s



EA440

EA440



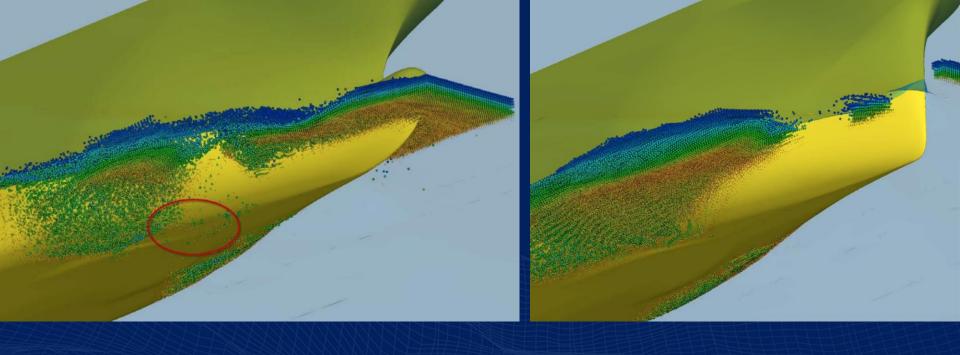


CFD Study

- Skipsteknisk
- Marin (MAritime Research Institute Netherlands)

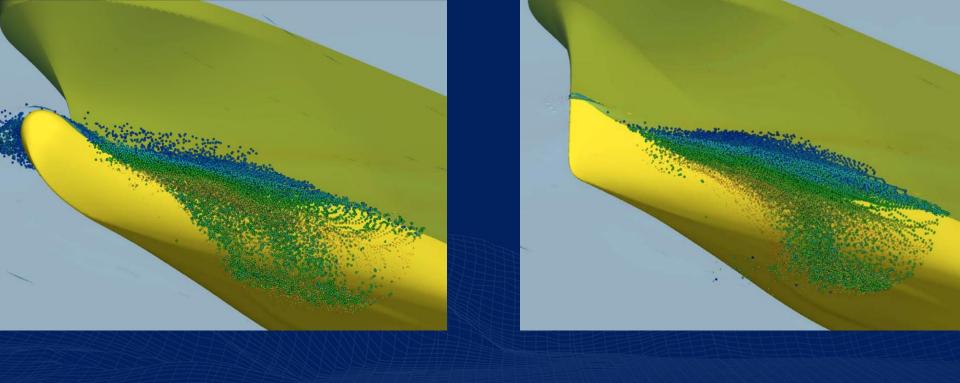
Two conditions were selected and simulated for three hull variants.





Bow Seas - The bow head seas condition has a regular wave of 13 seconds period and 2.3m amplitude; vessel speed 7 kts.





Quarter Seas - The bow quartering condition has a regular wave of period 13s and amplitude 4.2m, with heading 120 degrees off the bow coming from the port side; vessel speed 7 kts.

